



Locations:

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Introduction to LS-DYNA®

Instructor will be either: A Tabiei, A. Nair, R Chivukula, H. Devaraj, S. Adya

4 Days - \$750, Students \$375 w/student ID

Includes on-site continental breakfasts, lunches, breaks, class notes, class dinner

Includes 30-day demonstration license

Prerequisite: Students should be familiar with basic Finite Element methods.

Objective: Provide an introduction to LS-DYNA where basic capabilities are reviewed. Detailed descriptions and requirements are given for data preparation with examples. Pre- and post-processing using LS-PrePost is covered.

Description: This course is recommended for those who perform nonlinear static and transient simulations. Attendees working in nearly all fields of engineering will benefit. This course is a prerequisite for the advanced courses covering the multi-physics capabilities which include compressible and incompressible fluids, the airbag particle method, Arbitrary Lagrangian-Eulerian (ALE) fluids, thermal, acoustics, vibro-acoustics, metal forming, electromagnetics, discrete elements, failure, frequency response methodology, and isogeometric analysis.

LS-DYNA Contents:

Contents

- Course Outline
- History
- Finite Element Simulation
 - Sample LS-DYNA Conference Presentations
 - Sample Simulations
- FE Analysis (preprocessors, solver, postprocessors)
- Details of an Example
 - LS-DYNA Deck
 - Using LS-POST
 - Details of Postprocessing
- Detailed Capabilities-Keywrod Format

- Material Nonlinearity
- Running LS-DYNA
 - Execution and Output Files
 - § ASCII
 - § Binary
- Output Control
- FE Modeling Techniques
 - Engineering a FEA Model
 - Element Selection
 - § Discrete (formulation of elastic and nonlinear elastic spring)
 - § Beam
 - § Shell (description of the various shell formulations)
 - § Solid (description of the various solid formulations)
 - § Thick Shell
 - Boundary, and Initial Conditions, Symmetry
 - Modeling for Physical Phenomenon
 - Ad-Hoc Guidelines
 - How to Tell if your Results are Correct
 - § Error, debugging, and other useful information (d3hsp)
- Time Integration
 - The Equations of Motion
 - § Implicit
 - § Explicit
- Explicit Time Integration
 - Time Step Calculation
- Reduce–Selective Integration
- Hourglass Phenomenon
- Contact and Slide Surfaces
 - Friction
- Damping
- Restart
- Quasi-Static Simulations
 - Why Static Analysis With Explicit Code
- Mass Scaling